# Parrot



**User Guide** 

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# Before you begin

Note: The GPS must be connected to your AR. Drone 2.0.

#### Download the software

You can download the QGround Control free software on this website:

 $\underline{\text{http://qgroundcontrol.org/downloads}}.$ 

### Compatibility

In order to use the QGround Control software, your computer (PC, Mac or Linux) must be connected to the internet.

# Using the QGround Control Software

#### Completing a flight plan

To complete a flight plan, you must preload the map from a computer connected to the internet.

- 1. Launch the QGround Control software.
  - > A map is displayed.
- 2. Look for the location where you want to complete your flight plan. To do so:
  - a. Click and drag the cursor to move on the map.
  - b. Use the bar located on the right of your screen to zoom in/out.

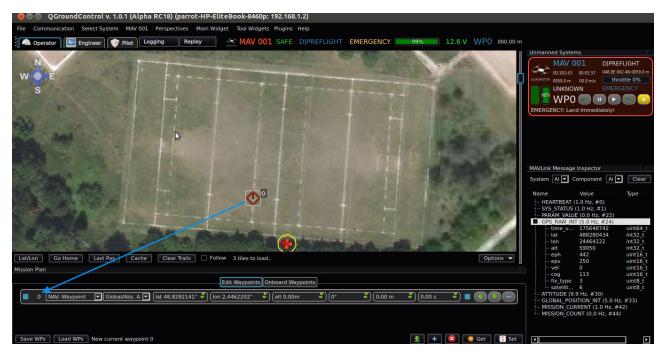
Note: Once the map pre-loaded, you don't need to be connected to the internet.

On the location of the flight plan:

- 1. Launch the QGround Control software.
  - > The pre-loaded map is displayed.
- 2. Connect your computer to the AR. Drone 2.0 via Wi-Fi.
  - > The AR.Drone 2.0 appears on the map.
- Click on Tool Widgets and select MAVLink Message Inspector.
  - > A window is displayed on the right of your screen.
- 4. Make sure that the EPH value is less than 1000.

```
MAVLink Message Inspector
System Al ▼ Component Al ▼
                                  Clear
   HEARTBEAT (1.0 Hz, #0)
    SYS STATUS (1.0 Hz, #1)
       lat
                 24464131
       lon
                 58690
       alt
      eph
                 191
       epv
                 113
       coa
    ATTITUDE (9.8 Hz, #30)
    GLOBAL POSITION INT (5.0 Hz, #33)
    MISSION CURRENT (1.0 Hz, #42)
```

- 5. Double-click on the map to create waypoints.
  - > The waypoint created is displayed at the bottom of your screen. The latitude and longitude are automatically generated.



- 6. Click on SET to create the flight plan and on GET to confirm it.
- 7. Click on the Take Off button
  - > You can control your AR.Drone 2.0. For more information, refer to the <u>Controlling the AR.Drone</u> <u>2.0 during a flight</u> section.

Note: If the EPH value is more than 1000, move your AR. Drone 2.0.

## Modify the settings of a waypoint

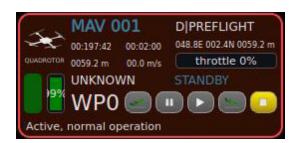


Bouton	Signification
1	Number of the waypoint
2	Type of the waypoint
3	Latitude of the waypoint (automatically generated)
4	Longitude of the waypoint (automatically generated)
5	Altitude of the waypoint
6	Orientation from North (in degrees) of the AR.Drone 2.0
	Area (in meters) around the waypoint the AR.Drone 2.0 must reach before heading
(7)	towards the next waypoint
	Length of time (in seconds) during which the AR.Drone 2.0 stays in the area of the
(8)	waypoint
9	Changing the number of the waypoint
(10)	Delete the waypoint

Note: To modify the maximum altitude of the AR. Drone 2.0, set to 3m by default, use the free application Free Flight (available on the App Store<sup>SM</sup> and on Google Play<sup>TM</sup>).

### Controlling the AR.Drone 2.0 during a flight

The interface located on the right of your screen allows you to control the AR.Drone 2.0.



Boutons	Signification
19%	Battery level of the AR.Drone 2.0
WP0	Waypoint where the AR.Drone 2.0 is (WPO, WP1, etc.)
	Take Off
-	Pause
	Restart of the AR.Drone 2.0
No.	Landing
	Emergency landing*

<sup>\*</sup>Warning: Press the button only in case of emergency! If you press the button, the engines will shut off and the AR.Drone 2.0 will fall out of the air. In most cases, landing the AR.Drone 2.0 is a better solution.

# **General information**

#### **Modifications**

The explanations and specifications in this guide are given for information only and may be modified at any time without prior notice. The explanations and specifications contained in this guide are deemed to be correct at the time of printing.

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